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)When conducting research, all members of the collaboration are required to complete a Data Usage Agreement that addresses the various intellectual property, intellectual property transfer, confidentiality, and access agreements that are in place between the investigators of the project. Disclaimer NIEHS disclaims all liability for any loss, injury, or damage caused by your reliance on information contained in this website, including injury or death caused by your use of any product or instruction mentioned at this site. The information presented in this website is for general educational purposes only. It is not intended as medical advice. Only a health care professional can provide medical advice. NIEHS and the U.S. and states government do not endorse any products or commercial services mentioned or advocated in this publication. Researchers at the University of Sussex in England have discovered a 3D shape-shifting robot that can be programmed using a mobile device. In the short clip that accompanies the research report, the small 5-ounce robot moves from a flat, side-on shape to a three-dimensional, upside down pose by snapping together the legs of its flexible robot. "The robot has a surprising ability to change its shape, and we're excited by the possibilities of this robotic technology," said researcher and co-author Julian Kuczynski in a press release. "We can make the robot into any shape or pattern and its real-time shape changes mean we can create any desired design." The robot's upper body is comprised of a lightweight plastic that's connected to its legs through hinges at the robot's base. The legs are connected at the tips with a thin, rigid strip that can be swiveled between open and closed positions, which allows the robot to assume three shapes, standing, laying down or standing on its tip. In the video, the robot is able to change from a flat, side-on pose to a three-dimensional, upside down pose by snapping together the legs of its flexible robot. An ideal robot of this type could be designed to complete a number of tasks. Kuczynski imagines a robot used to transport and set up tables at a restaurant, picking up a flat surface and rotating it into the needed shape. In the video, the robot lifts itself off a surface and stands on its tip. Other possible uses would include robotic swarm-based assembly, where multiple robots take on one project. "It's an example of a future world where robots work together, with many different

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